

USE AND MAINTENANCE MANUAL

SERIES

PRO

CE





CONTROL AND MANAGEMENT KIT FOR METERING PUMPS **KIT-PRO / KIT-PRO UL**

| Doc. No. | UT-5601 PULFL | Rev. 1 | Lang. | EN | 1st Issue | 05/19/2023 |
|-------------|---------------|---------|-------|----|-------------|------------|
| Prepared by | KR | Checked | by | | Replaced on | |

REVISION INDEX

| Chapters | Rev | Date | Rev | Date | Rev | Date | Rev | Date |
|----------|-----|------------|-----|------------|-----|------------|-----|------------|
| Index | 0 | 20/06/2018 | 1 | 05/10/2018 | 2 | 07/02/2019 | 3 | 24/06/2020 |
| 0 | 0 | 20/06/2018 | | | 2 | 07/02/2019 | | |
| 1 | 0 | 20/06/2018 | | | 2 | 07/02/2019 | 3 | 24/06/2020 |
| 2 | 0 | 20/06/2018 | | | | | 3 | 24/06/2020 |
| 3 | 0 | 20/06/2018 | | | 2 | 07/02/2019 | 3 | 24/06/2020 |
| 4 | 0 | 20/06/2018 | 1 | 05/10/2018 | | | 3 | 24/06/2020 |
| 5 | 0 | 20/06/2018 | 1 | 05/10/2018 | | | 3 | 24/06/2020 |
| 6 | 0 | 20/06/2018 | | | | | 3 | 24/06/2020 |
| 7 | 0 | 20/06/2018 | | | | | 3 | 24/06/2020 |
| 8 | 0 | 20/06/2018 | | | | | 3 | 24/06/2020 |

| Date | 24/06/2020 |
|-----------|------------|
| Signature | |

TABLE OF CONTENTS

| F | REVISION INDEX | 1 2 |
|------------------|---|------------------|
| 0 | INTRODUCTION | 3 |
| 1 2 | | |
| 1 | GENERAL INFORMATION | 4 |
| | CE MARKING UL MARKING DECLARATIONS UL CERTIFICATION | 4 5 6 7 |
| 2 | SAFETY | |
| 1 2 3 | I GENERAL SAFETY WARNINGS 2 USE RESTRICTIONS 3 ELECTROMAGNETIC COMPATIBILITY 4 SAFETY | 8 8 8 |
| 3 | INSTALLATION | 10 |
| | 2 STORAGE CONDITIONS 3 POSITIONING 4 ADJUSTMENTS 5 ASSEMBLY | 10 11 11 |
| 4 | PRODUCT DESCRIPTION | 15 |
| 1 2 3 2 | 2 MAIN COMPONENTS AND DIMENSIONS | 16 18 |
| 5 | USE AND SOFTWARE | 20 |
| 1 | | 20 |
| 6 | MAINTENANCE | 38 |
| 1 2 | ROUTINE MAINTENANCE ROUBLESHOOTING | |
| 7 | ACCESSORIES AND SPARE PARTS | 40 |
| 1 2 | ASSISTANCE SPARE PARTS | |
| 8 | ADDITIONAL INSTRUCTIONS | |
| 1 | L DECOMMISSIONING AND DISASSEMBLY | 41 |

0 INTRODUCTION

1 SCOPE OF THE USE AND MAINTENANCE MANUAL

This manual provides the user with general guidelines to use the product safely.

This User Manual is an integral part of the product and provides the following information about the product:

- technical specifications;
- a description of its operation and limits;
- instructions on how to use it under safe conditions;
- instructions on how to perform maintenance and repairs correctly and safely;
- technical support;
- instructions on waste disposal.

2 HOW TO READ THIS USER MANUAL

This manual is divided into chapters. Each one of them provides specific information.

NUMBERING OF THE FIGURES

Each figure is numbered progressively.

NUMBERING OF THE TABLES

Each table is numbered progressively.

The progressive number starts from 1 at every new paragraph.

ABBREVIATIONS

- Cap. = Chapter
- Par. = Paragraph
- Sec. = Section
- Page = Page
- Fig. = Figure
- Tab. = Table

1 GENERAL INFORMATION

1 MANUFACTURER'S IDENTIFICATION DATA

| MANUFACTURER | OBL S.R.L. |
|--|--|
| REGISTERED HEADQUARTERS AND ADMINISTRATIVE OFFICE | Via Kennedy 12 - 20090 Segrate (MILAN) ITALY |
| TELEPHONE NUMBER | 0039 02 26 91 91 |
| E-MAIL | Obl.info@idexcorp.com |

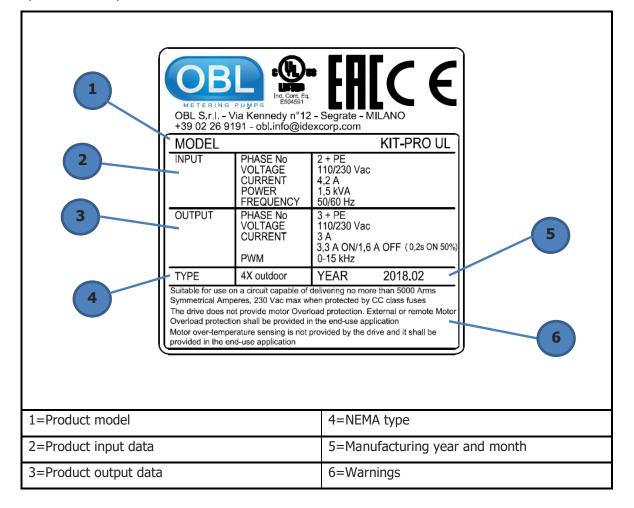
2 CE MARKING

Every KIT-PRO product is identified with a CE label indicating its reference data, which are printed indelibly.

| 1 | Via Kennedy n°12 - Segrat +39 02 26 9191 - obl.info@ | Didexcorp.com | |
|------------------------|---|---------------------------------|--|
| | MODEL | KIT-PRO 5 | |
| | 230 V | 50 Hz | |
| 3 | MAX CURRENT 4.2 A | MAX POWER 1500 VA | |
| | MAX MOTOR POWER | 750 W | |
| | ENCLOSURE | IP65 6 | |
| | SERIAL No. 2018 | P4831 06/2018 | |
| | | 8 | |
| 1=Product model | | 6=Protection rating | |
| 2=Power supply voltage | | 7=Serial number | |
| 3=Maximum cur | rrent consumption | 8=Month and year of manufacture | |
| 4=Power supply | frequency | 9=Max power of the motor | |
| 5=Maximum por | wer consumption | | |

3 UL MARKING

Every KIT-PRO UL product is identified with a UL label indicating its reference data, which are printed indelibly.



CE

EU DECLARATION OF CONFORMITY (UT5604-0) (ANNEX IV, DIR. 2014/35/EU) THE MANUFACTURED

| THE PARTOR ACTORER | | | | | |
|---------------------------|---|--|--|--|--|
| COMPANY NAME | OBL SRL | | | | |
| ADDRESS | VIA KENNEDY 12, 20090 Segrate – MILAN - Italy | | | | |
| DECLARES THAT THE PRODUCT | | | | | |

| NAME | MODEL |
|---------|---------|
| KIT PRO | KIT PRO |

COMPLIES WITH THE FOLLOWING EUROPEAN DIRECTIVES

DIRECTIVE 2014/35/EU of the European Parliament and Council, dated 26 February 2014, on the harmonisation of the laws of the Member States relating to the making available on the market of electrical equipment designed for use within certain voltage limits

DIRECTIVE 2014/30/EU of the European Parliament and Council, dated 26 February 2014, on the harmonisation of the laws of the Member States relating to electromagnetic compatibility (recast)



AND THAT THE FOLLOWING STANDARDS HAVE BEEN APPLIED (PARTS/ARTICLES OF HARMONISED STANDARDS)

EN 61800-5-1

Adjustable speed power drive systems - Part 5-1: Safety provisions - Electric, thermal, and energy safety

DATE AND PLACE

rate, 26/06/18

lie den

SIGNATURE

CERTIFICATE OF COMPLIANCE

Certificate Number Report Reference Issue Date

20181226-E504591 E504591-20181220 2018-DECEMBER-26

Issued to: OBL SrI Via Kennedy 12 20090 Segrate MI ITALY

This certificate confirms that POWER CONVERSION EQUIPMENT representative samples of Enclosed type 4X – Power Conversion Equipment – Motor Drive Model KIT-PRO.

> Have been investigated by UL in accordance with the Standard(s) indicated on this Certificate.

Standard(s) for Safety: UL 61800-5-1, Adjustable Speed Electrical Power Drive Systems - Part 5-1: Safety Requirements - Electrical,

Additional Information:

See the UL Online Certifications Directory at https://ig.ulprospector.com for additional information.

Thermal and Energy and CSA C22.2 No. 274-17,

This Certificate of Compliance does not provide authorization to apply the UL Mark.

Only those products bearing the UL Mark should be considered as being UL Certified and covered under UL's Follow-Up Services.

Adjustable Speed Drives

Look for the UL Certification Mark on the product.

Simule

Page 1 of 1

6 TECHNICAL SUPPORT - INFORMATION

This product is guaranteed as stated in the general terms and conditions of sale. Should malfunctions or failures (included within the cases covered by the warranty) be detected during the warranty period, the Manufacturer will repair or replace the defective parts, prior to verification.SAFETY

2 SAFETY

1 GENERAL SAFETY WARNINGS

The Manufacturer has designed this product to make it as SAFE as possible.

Every OBL KIT PRO is a reliable, quality product, which undergoes careful end inspection to ensure proper operation and ascertain compliance with specified performance.

The Manufacturer of the machine must install the product and comply with all the regulations and safety standards in force in the country of installation.

Attention! When using mains-powered equipment, always follow basic safety precautions, including the following, to reduce damage to people and property:

Carefully read the instructions in this manual before installing/using the device.

Keep these instructions for future use.

2 USE RESTRICTIONS

The PRO KIT can be installed only and exclusively on the following pump models:

- 1. OBL's metering pumps of the Black Line series (M diaphragm version)
- 2. OBL's metering pumps of the Black Line series (R piston version)
- 3. OBL's metering pumps of the Black Line series (XRN version)

3 ELECTROMAGNETIC COMPATIBILITY

The user is the only responsible for solving problems related to electromagnetic compatibility once the finished product is completely produced. In some cases, the equipment needs to be earthed correctly, while in others a screen may be required. The manufacturer of the KIT PRO is available to help the user solve problems related to electromagnetic compatibility upon request.

4 SAFETY

- Carefully read this use and maintenance manual before starting, using, performing maintenance, or any other operation on the equipment.
- Strictly comply with the warnings contained in the manual, whether they indicate danger or caution.
- The operator must meet all the requirements for using this type of machine.
- Always wear personal protective equipment in compliance with the occupational safety regulations in force.
- Before proceeding with the installation, make sure that the area does not feature any dangerous condition. Make sure no foreign bodies have been left inside or on the machine.
- Start the machine start-up sequence following the instructions.
- Do not enter the machine's operating area while the machine is running.
- Do not introduce your hands or anything else near or inside the equipment live parts.
- Do not work in dark conditions. Use all the lights available, making sure they are efficient.
- Do not use the machine when under the influence of medicines or alcohol, as they may impact your capacity of moving and thinking.
- Stay concentrated and use caution before carrying out any operation.
- Always keep the work area clean.
- Warn the maintenance managers about any malfunction of parts or systems on board the machine.
- Do not wear loose clothing, but always accident-prevention clothing.

<u>NOTE (for UL version)</u>: Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the National Electrical Code and any additional local codes.

CSA: INTEGRAL SOLID STATE SHORT CIRCUIT PROTECTION DOES NOT PROVIDE BRANCH CIRCUIT PROTECTION. BRANCH CIRCUIT PROTECTION MUST BE PROVIDED IN ACCORDANCE WITH THE CANADIAN ELECTRICAL CODE, PART I.

5 SAFETY PICTOGRAMS

The device is installed on OBL metering pumps. Pay attention to the safety pictograms on the pumps.

3 INSTALLATION

1 TRANSPORT AND HANDLING

The KIT-PRO / KIT-PRO UL can be handled manually as it weighs only 5 kg. Always transport the product inside its original packaging.

2 STORAGE CONDITIONS

If not used immediately, the KIT-PRO/KIT-PRO UL should be stored with suitable covers in a temperate, dry, clean, vibration-free and weatherproof environment. Protect from soil moisture by placing the unit on shelves or wooden pallets. If the temperature is below 0°C, ensure that it does not go lower than -10°C. If not specifically highlighted on the package, do not stack packaging, to prevent damage to the KIT-PRO and to avoid tipping over or falling that can create accidents. Ensure that access of unauthorized persons is not allowed in the storage location and that the floor or shelf can support the weight of the machinery or equipment stored. Take additional safety measures in the case of storage in extreme conditions, i.e. in sub-tropical or desert climates.



Report special storage conditions in advance in order to provide for adequate packaging.



Check the dimensions and overall gross weight of the package before handling or lifting it.

3 POSITIONING

The Black Line 2.0 M and R pumps can be installed on a KIT-PRO, as shown in Figure 1.

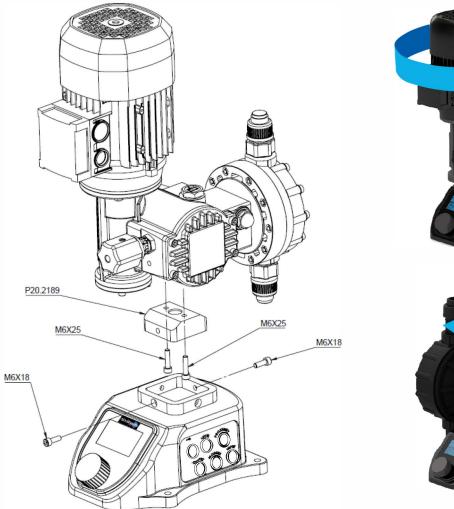




Figure 1 Installation of the KIT

Moreover, the orientation of KIT-PRO / KIT-PRO UL can be changed from 0 to 90° compared to the pump. To carry out this operation, you just have to:

- 1. unscrew the 2 screws (M6x18)
- 2. rotate the pump
- 3. tighten the 2 screws (M6x18)

4 ADJUSTMENTS

See chapter 5 "USE AND SOFTWARE".

5 ASSEMBLY

The KIT PRO /KIT PRO UL can be supplied in two versions:

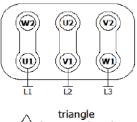
- Assembled on an OBL metering pump (Black Line series)
- The assembly kit can be assembled and installed on an OBL Black Line 2.0 metering pump (manufactured from May 2017 onwards)

The KIT PRO must be assembled on pumps not installed in a system. <u>Contact an OBL</u> <u>distributor in the event the OBL pump on which the KIT PRO is to be installed is</u> <u>already operating in a system</u>.

The KIT PRO is suitable for all OBL metering pumps of the Black Line series with a standard motor (three-phase power supply 380V/230V/110V 50/60 Hz). Contact an OBL distributor in the event motors with different characteristics are installed.

Follow the instructions below to assemble the KIT PRO on OBL's Black Line metering pumps:

- 1. Make sure the motor is not powered
- 2. Make sure that the OBL metering pump on which the KIT PRO is to be installed is not running.
- 3. Disassemble the base of the Black Line pump (pos. 117 in the BL2.0 M and R section drawings)
- 4. Mount connection P20.2189 (Figure 1) using the M6x25 screws.
- 5. Fasten the KIT PRO to the connection (Figure 1) using the provided M6x18 screws.
- 6. Disconnect any connection to the electric motor terminal box of the Black Line metering pump.
- 7. Connect the KIT PRO's output cable to the terminal box of the Black Line pump's motor, making sure that the connection is <u>delta (230 V)</u> like the picture on the side. Refer to the use and maintenance manual of the Black Line metering pump, chapter 2 paragraph 6, and chapter 8. In the following table please find the information regarding colour conductors associated to the interconnection of the motor and power supply. The device shall be connected using this information.



$\triangle \quad \frac{\text{triangle}}{(\text{Lower voltage})}$

Table 1 Motor and power supply interconnetions

| CONNECTOR | CONDUCTOR | KIT-PRO CONDUCTOR | KIT-PRO UL |
|-------------|-----------|-------------------|------------------|
| CABLE GLAND | FUNCTION | COLOUR | CONDUCTOR COLOUR |
| | U | Blue or Grey | Red |
| MOTOR | V | Brown | White |
| HOTOK | W | Black | Black |
| | GROUND | Yellow/Green | Green |
| | L | Black or brown | Black |
| POWER | N | Blue | White |
| | GROUND | Yellow/Green | Green |

8. KIT-PRO must be fixed to a stable support by tightening the M8 screws into the Ø8.5 holes on the body (Figure 2).

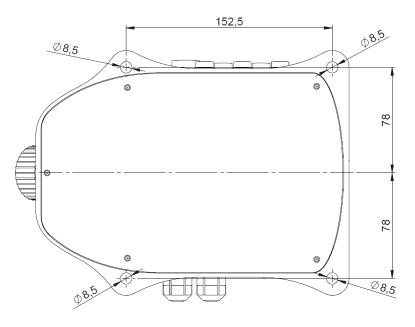


Figure 2 Fastening holes

9. <u>Before making electrical connections, make sure that the power mains voltage</u> <u>matches the information contained on the KIT PRO /KIT PRO UL data plate.</u>

6 ELECTRICAL CONNECTIONS

6.1 Power supply connection

The cable glands should be tightened so that seal rings keep the necessary pressure:

- to prevent transmission of mechanical stress on the motor terminals
- to ensure mechanical protection (IP degree) of the terminal box

\perp <u>NOTE</u>: Always make the earth connection using the appropriate earth wire on the main power cable.

<u>NOTE:</u> In the event of power outage or disconnection, let the screen switch off before reconnecting the power supply.

<u>NOTE:</u> For KIT-PRO UL cable glands should be tightened considering the following torques:

- 1. Panel I/O Cable Gland = in-lbs (N-m)= 79.6 (9)
- 2. Power Cable gland: in-lbs (N-m) = 97 (11)

6.2 Signal connection

The KIT PRO has different signal connections, whose name are shown on the enclosure.

The KIT includes the relative connectors, which are provided with a 1-meter cable. The cables supplied feature 4 conductors featuring different colours. The function of the input cables changes depending on the hardware version. Please check the hardware operating on the controller in the menu settings→firmware info→version. The version of the hardware can be 0.1 or 0.2 (from the end of 2020). Table below **Error! Reference source not found.** shows the connectors needed. **Table 2 Connectors**

| CONNECTOR | PIN FUNCTION | KIT-PRO | KIT-PRO UL |
|-----------------|--|-----------|------------|
| | | CONDUCTOR | CONDUCTOR |
| | | COLOUR | COLOUR |
| | Remote Start/Stop (contact) | Yellow | Red |
| | Pulses (contact) | Green | Green |
| INPUT (HW 0.1) | Ground (-) | Brown | White |
| | (common for all pins of input connector) | | |
| | 4-20 mA/0-10V analogue (+) | White | Black |
| | (passive signal: power supply needed) | | |
| | Remote Start/Stop | Yellow | Red |
| | Remote Ground | Green | Green |
| INPUT (HW 0.2) | 4-20 mA/0-10V/pulse (-) | Brown | White |
| INFOT (INV 0.2) | (passive signal: power supply needed) | | |
| | 4-20 mA/0-10V/pulse (+) | White | Black |
| | (passive signal: power supply needed) | | |
| | А | Yellow | Red |
| MODBUS | В | Green | Green |
| | Ground (-) | Brown | White |
| | 4-20 mA analog (+) | Yellow | Red |
| | (passive signal: power supply needed) | | |
| OUTPUT (HW | 4-20 mA analog (-) | Brown | White |
| 0.1) | (passive signal: power supply needed) | | |
| | Relays | Green | Green |
| | Relays | White | Black |
| | 4-20 mA analog (+) | Yellow | Red |
| | (active signal: no power supply needed) | | |
| OUTPUT (HW | 4-20 mA analog (-) | Brown | White |
| 0.2) | (active signal: no power supply needed) | | |
| | Relays | Green | Green |
| | Relays | White | Black |
| LEVEL | Start | Green | Red |

| | Stop | Yellow | Green |
|---------------|--|---|-------|
| | Ground | Brown | White |
| | (common for all pins of level connector) | | |
| | VBUS | | Red |
| USB 2.0 HOST | D- | Suitable for the connection | Green |
| 030 2.0 11031 | D+ | of a USB flash | White |
| | Ground | drive | Black |
| Proximity | 0 V | Suitable for the connection | Red |
| | Proximity | of the supplied proximity sensor. | Green |

6.3 Connecting the stroke counter sensor (proximity)

The stroke counter sensor Figure 7 is provided with the KIT PRO.

To install it, you just have to:

- 1. Loosen the oil cap (pos. 119 of the section drawing)
- 2. Tighten the proximity sensor in the oil cap housing
- 3. Connect the proximity sensor to the electronics using the appropriate connector

The proximity sensor is supplied with a spacer. Use the spacer on the M version of the KIT PRO and remove it from the R version.

<u>NOTE</u>: Always make the connection using the appropriate connector. Do not use or connect other inductive sensors to the proximity connection. Make all the connections only when the pump is at a standstill.

4 PRODUCT DESCRIPTION

1 OPERATING PRINCIPLE

The KIT PRO is a management and control system for OBL's Black Line metering pumps. The KIT PRO can adjust the flow rate, changing the number of revs of the pump's electric motor. The KIT PRO has different operating modes (cf. chapter 5) to manage the pump's flow rate.

The KIT PRO can receive an input alarm signal from the instruments installed on the metering system, such as the level sensors.

The KIT PRO is provided with a display from where you can see the pump's operating status and enter the flow rate parameters. The different operating statuses of the pumps have different colours:

- Operating mode colour (green, blue, azure, lilac): correct operation
- Yellow: incorrect yet not dangerous operation

- Red: incorrect operation and pump lock

The PRO KIT does not adjust the stroke of the metering pump (cf. Use and maintenance manual of the Line Black pump, chap. 10.2).

The KIT PRO adjusts the ratio between maximum and minimum flow rate provided, as it adds the possibility to vary the number of revs of the electric motor and adjust the pump's stroke. This way, the turndown ratio can be of 500:1.

<u>NOTE</u>: The system does not automatically record every adjustment. Therefore, the flow rate and volume indicated by the software may differ from those actually provided, unless a calibration procedure is carried out (Table) with the new adjustment position.

2 MAIN COMPONENTS AND DIMENSIONS

As shown in the following figures, the KIT PRO consists of:

- 1. 1 enclosure containing the electronic control unit
- 2. 1 connection
- 3. 1 proximity sensor
- 4. 4 connectors with a 1-meter cable

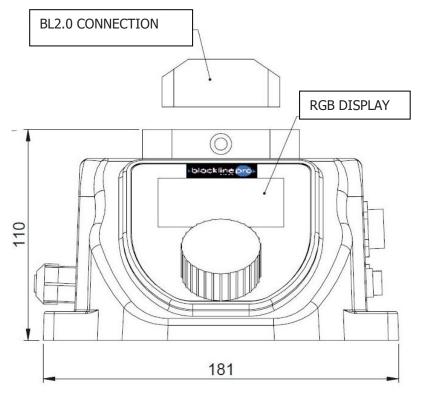
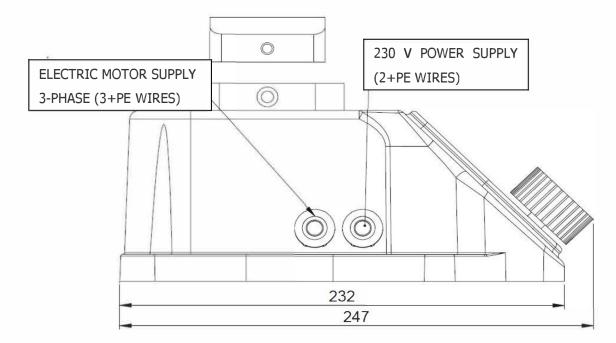


Figure 3 Front view





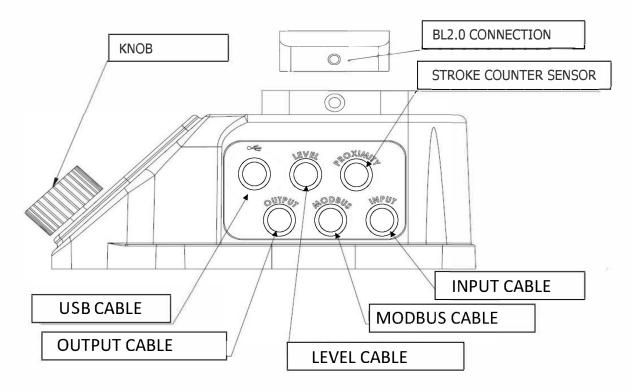


Figure 5 Side view of the supply lines

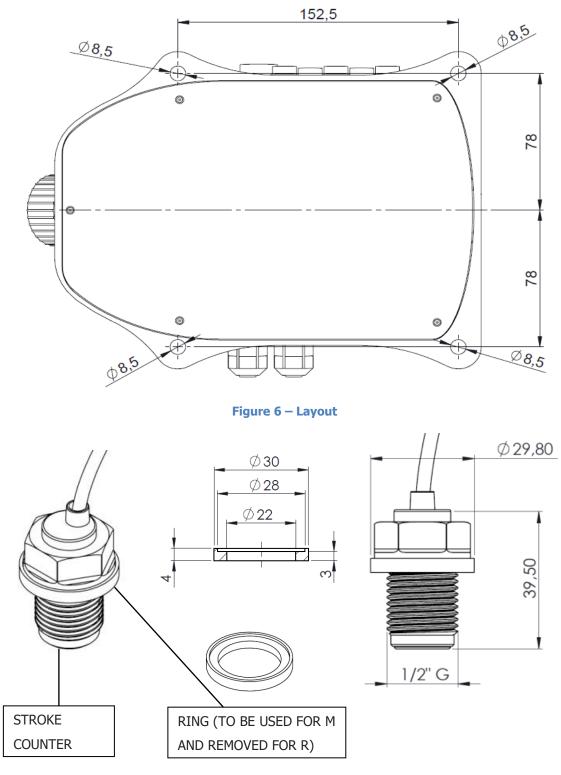


Figure 7 stroke counter sensor and ring

3 ENVIRONMENTAL CONDITIONS

As for installation, the environmental conditions must match the possible use conditions of OBL's metering pumps, which can be combined with the KIT PRO.

This product shall be used in Pollution degree 2 Environment.

4 TECHNICAL DATA

The KIT PRO is suitable for all OBL's metering pumps of the Black Line series with a standard motor (three-phase power supply 230/380V 50 Hz). Contact an OBL distributor in the event motors with different characteristics are installed.

Table 3- Technical data

| | | | М | R | | |
|-----------------|-----------------------|--------------------------------------|--------------------------|----------------------------|--|--|
| | Max. flow rate (| @ 1,5 bar) | 800 lt/hr | 1050 lt/hr | | |
| | Max pressure | | 12 bar | 40 bar | | |
| | Max. stroke free | quency | 155 strokes/min | 114 strokes/min | | |
| | Max. suction lift | | 1,5 m | 1,5 m | | |
| lata | Liquid temperat | ure | -10°C÷+40°C | -10°÷+90°C | | |
| alo | Max. weight | | 28 Kg | 26 Kg | | |
| Mechanical data | Accuracy | | +/- 3% | | | |
| scha | Linearity | | | +/- 5% +/- 3% | | |
| ž | Repeatability | | | 3% | | |
| | Turndown ratio | | | 0:1 | | |
| | Sound pressure | | | dbA | | |
| | | ator, casing, motor) | | ninum | | |
| | Finishing (actua | | | deposition (EPD) | | |
| | Max power cons | · | | 00W | | |
| | Max motor pow | er | | 0W | | |
| | Max output cur | rent | | ff (0,2 s ON 50%) 100%) | | |
| Ita | Max input curre | nt | 4.: | 2 A | | |
| Electrical data | Power Supply | | 110 V AC 230 V AC | | | |
| ctri | Frequency | | 50/6 | 50 Hz | | |
| E | Operating temperature | | -10/40 °C | 14/113 °F | | |
| | Max inrush curr | ent | 2,3A (110V) 5A (230V) | | | |
| | Enclosure class | (actuator only) | IP65 | | | |
| | Recommended | fuse | 6,3 x 32 | 2mm 8A | | |
| USB | Туре | | USB 2. | 0 HOST | | |
| Serial | MODBUS RTU | | Half Dupl | ex RS-485 | | |
| | 4.20 | Max input Voltage /Control input | 14 | V DC | | |
| | 4-20 mA | Impedance | 12 | 0 Ω | | |
| | 0.4014 | Input Voltage /Control input passive | 10 V DC | | | |
| <u>ц</u> | 0-10 V | Impedance | 15 | kΩ | | |
| Input | Pulse (PNP) | Voltage Range High Level | Min 19V DC - | Min 19V DC - Max 29 V DC | | |
| - | | Max resistance in pulse circuit | 15 | ΚΩ | | |
| | | Min pulse length | 10 | ims | | |
| | Remote | Max load START/STOP digital input | 28 V DC | | | |
| | Level | Max load STOP digital input | | / DC | | |
| | | | | | | |

| | | Max load START digital input | 28 V DC |
|-----------------|----------------------|------------------------------|------------|
| 4W 0.1) | 4-20 mA (passive) | Input Voltage /Control input | 48 V DC |
| Output (HW 0.1) | Relays | Max load | 24 V DC 3A |
| (7 | 4-20 mA (active) | Max Out Voltage | 21 V DC |
| Output (HW0.2) | | Max impedance | 750 Ω |
| nO | Relays | Max load | 24 V DC 3A |

5 USE AND SOFTWARE

1 INTERFACE

The user interface consists of an encoder with a knob, which allows you to carry out two operations:

Table 1 Interface

| ROTATION | Turn the knob to move a selector switch to | |
|----------|--|--|
| | the required item. Moreover, you can | |
| | increase or decrease the value of a selected | |
| | item. | |
| CLICK | Press the knob to confirm a selected value | |
| | or access different items of the menu. | |

2 ICONS

The icons used in the program and relative function are summarised in the following table:

Table 5 Icons

| ICON | FUNCTION |
|------|-----------|
| ۵ (| Main Menu |

| lı. | Statistics |
|----------|-------------------------|
| | Settings |
| ¢ | Previous page |
| Ċ | Off |
| • | Start |
| | Stop |
| A | Alarm |
| G | Manual adjustment value |
| 2 | Operating frequency |
| പി | Flow partialisation |
| <u>×</u> | Reset |
| – | Modbus |

3 MENU

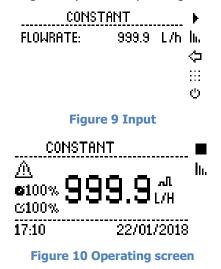
3.1 Home page



Figure 8 Home page

3.2 Operating modes

From the home page, click "operating modes" to select the operating mode you need. Each mode features an input screen (Figure 9Figure 10) and an operating screen (Figure 10).



File: UT-5601 PULFL Copyright © - OBL Metering pumps - All rights reserved

You can change the mode operating parameters or carry out operations by using the icons on the right side of every input screen:

- 1. Start: to start the set mode
- 2. Statistics (Figure 11): you can view:
 - a. The volume provided and the partial resettable activation time (by clicking on the reset icon)
 - b. The volume provided and the total non-resettable activation time

| STATS | | |
|------------------------|-----------|-----|
| PARTIAL VOL. 900.00 L | | ¥. |
| PARTIAL LIFE 00d00h00m | | ⊅ |
| TOTAL VOL. | 600.00 L | ::: |
| TOTAL LIFE | 00d00h00m | ප |

Figure 11 Statistics

- 3. Back: to return to the previous menu
- 4. Settings: to open the setting menu
- 5. Off: to set the electronics in standby.

The operating modes available are shown in the following table:

Table 6 Operating modes

| Modes | Input parameters | Description |
|------------|---|---|
| Constant | FLOW RATE | The pump runs at a constant flow rate |
| Batch | VOLUME FLOW RATE START (MANUAL OR EXTERNAL) | The pump doses the volume of liquid at the set flow rate. Upon manual start, the process is repeated once and then it stops. Upon external start, the pump waits for the signal to start based on the set parameters and waits for a signal to repeat the process again. |
| PPM | PPM CONCENTRATION PULSE/L (L/PULSE) TIMEOUT | When the pump receives an external input signal sending pulses, it doses the liquid based on the liquid concentration value and ppm required at destination. The PULSE/L and L/PULSE parameters allow you to set the characteristics of the meter. The TIMEOUT parameter considers the maximum interval between two subsequent pulses. |
| Percentage | PERCENTAGE CONCENTRATION PULSE/L (L/PULSE) TIMEOUT | When the pump receives an external input signal sending pulses, it doses the liquid based on the concentration value of the liquid and the concentration required at destination (Percentage). The PULSE/L and |

| | | L/PULSE parameters allow you to set the characteristics of the meter. The TIMEOUT parameter considers the maximum interval between two subsequent pulses. |
|------------|--|---|
| MLQ | MLQ CONCENTRATION PULSE/L (L/PULSE) TIMEOUT | When the pump receives an external input signal sending pulses, it doses the liquid based on the concentration value of the liquid and millimetres per quintal (MLQ) required at destination. The PULSE/L and L/PULSE parameters allow you to set the characteristics of the meter. The TIMEOUT parameter considers the maximum interval between two subsequent pulses. |
| Pulse | MAXIMUM PULSE VALUE/M MINIMUM PULSE VALUE/M MAXIMUM FLOW RATE MINIMUM FLOW RATE TIMEOUT | When the pump receives a pulse input signal, it adjusts the flow rate based on the value of pulses per minute received between the maximum and minimum values. The TIMEOUT parameter considers the maximum interval between two subsequent pulses. |
| Analog mA | MA MAXIMUM VALUE (20 MA) MA MINIMUM VALUE (4 MA) MAXIMUM FLOW RATE MINIMUM FLOW RATE RANGE ALARM | The pump adjusts the flow rate based on an external analog signal and the maximum and minimum values set in the inputs. |
| Analog V | MAXIMUM V VALUE (10 V) MINIMUM V VALUE (0 V) MAXIMUM FLOW RATE MINIMUM FLOW RATE RANGE ALARM | The pump adjusts the flow rate based on an external analog signal and the maximum and minimum values set in the inputs. |
| Pause-work | FLOW RATE OPERATING PERIOD (MIN) PAUSE PERIOD (MIN) | The pump alternates pause periods with constant flow rate operation periods whose duration can be set. |

| Weekly | SET A PROGRAM: | This menu allows you to set the data |
|--------|--------------------|---------------------------------------|
| | PROGRAM No. | of each program (max 13 programs). |
| | DURATION | You can set the constant flow rate or |
| | START TIME | volume of constant flow rate to be |
| | CONSTANT FLOW RATE | transferred, transfer duration, start |
| | VOLUME | time, and days of activity. |
| | DAYS OF ACTIVITY | We recommend not overlapping the |
| | | programs. |
| | | |
| | | |
| | ACTIVE PROGRAMS | This menu shows the active |
| | | programs and allows you to activate |
| | | or deactivate them. |

3.3 Partialisation

In the event that the required flow rate is 30% lower than the set flow rate during calibration, the pump starts the partialisation stage. This stage consists in:

- 1. Work stage, in which the pump runs at 30%
- 2. Pause stage

The duration of these two stages are calculated by the firmware so as to obtain the flow rate required.

The minimum flow rate provided is 1% the maximum flow rate. The pump fails to start if this value is not reached.

3.4 Settings

The setting menu is shown in Figure 12 and allows you to open all the functions described in Table

| SETTINGS | |
|---------------|---|
| ∧ CALIBRATION | |
| PUMP CAPACITY | â |
| PRIMING | G |
| V LANGUAGE | ė |

Figure 12 Settings

Table 7 Settings

| Modes | Input parameters | Description |
|-------------|-----------------------------|-------------------------------------|
| Calibration | TEST DURATION | This mode allows you to test the |
| | MOTOR POWER | pump's flow rate at the maximum |
| | MAXIMUM MOTOR PHASE CURRENT | frequency. The pump capacity screen |
| | MOTOR FREQUENCY | appears at the end of the test. |

| | | Moreover, you can set the test |
|---------------|------------------------------------|---|
| | | pressure (for test purposes only). |
| | | Moreover, you can set the motor |
| | | phase current (depending on the |
| | | power) so that the system can block |
| | | the pump once this current value is |
| | | exceeded (table 8:motor short-circuit |
| | | alarm). The system saves the date of |
| | | the last test performed. NOTE: it is |
| | | good practice to calibrate the |
| | | pump every time process |
| | | conditions change (pressure, |
| | | manual adjustment value, etc.). |
| Pump capacity | MAXIMUM FLOW RATE | In this screen, you can enter the flow |
| | TEST VOLUME | rate or volume obtained during |
| | ADJUSTMENT | calibration. The maximum flow rate |
| | TEST PRESSURE | set will never be exceeded in the |
| | DATE OF THE LAST TEST | operating modes. The adjustment |
| | PERFORMED | value is displayed in the operating |
| | | screen. |
| Priming | PRIMING TIME | Set the priming time and click start |
| Philling | PRIMING TIME | |
| | | to start the priming function. Press |
| | | stop to stop the priming function. |
| Languages | IT EN ES FR NL RU DE TU | Select language |
| Password | USER | Set the 4-digit password for each |
| | ADMIN | user (it blocks the parameter setting |
| | | of the operating modes) or |
| | | administrator (it blocks the access to |
| | | settings). |
| DATE & CLOCK | DATE FORMAT (DD/MM/YY) | You can choose how you want to |
| | TIME FORMAT (24/12 H) | display the date and time. These |
| | DATE | data are added to the statistics |
| | TIME | report. |
| UNIT OF | Flow Rate L/h and Gal/h. | Even the volume measurement units |
| MEASUREMENT | | are updated accordingly. |
| PROXIMITY | Alarm activation with red display. | The proximity sensor (supplied) |
| | | verifies the correct operation of the |
| | | pump. The firmware stops the pump |
| | | if the number of strokes is equal to 0 |
| | | |

| | | with active pump. An error is |
|-------------------|------------------------------|---|
| | | recorded in the report. The error can |
| | | be reset in the alarm log. |
| | | be reset in the daminog. |
| FIRMWARE INFO | INFO | This screen allows you to interface |
| | UPDATE FIRMARE | with the USB port, through which |
| | EXPORT PARAMETERS | you can update the software, import |
| | IMPORT PARAMETERS | and export parameters, export and |
| | EXPORT LOG | delete reports, check the software |
| | DELETE LOG | version, and restore the default |
| | RESTORE TO FACTORY SETTINGS | settings of the system. Export the |
| | | report before updating the software |
| | | so as not to erase the log file from |
| | | the system. |
| MODBUS | MODBUS (YES/NO) | This setting allows you to control the |
| | BAUD RATE | pump in Modbus. |
| | ADDRESS | |
| ANALOG OUTPUT | OUTPUT | Possibility to activate the output of a |
| | | proportional analog signal at the |
| | | operating frequency. |
| RELAY | OUTPUT (OFF / START/STOP / | This function allows you to use the |
| | ALARM) | relay with a N.O. or N.C. contact. |
| | CONTACT (N.O. /N.C.) | The output signal indicates the |
| | | pump's status (ON/OFF) or the |
| | | presence of an alarm. |
| DISPLAY | MENU' LIGHT (ON/OFF) | Display settings: backlight activation |
| | WORKING COLOUR (GREEN, PINK, | while browsing the menus, colour |
| | BLUE, AZURE) | selection in operating modes, |
| | CONTRAST (0-100%) | contrast. |
| LEVEL | STOP (YES/NO) | Setting for starting or stopping the |
| | CONTACT (N.O./N.C.) | pump remotely (usually from a level |
| | RED ALARM DISPLAY (YES/NO) | sensor). You can also decide whether |
| | START (YES/NO) | to activate the red display with the |
| | CONTACT (N.O./N.C.) | pump at a standstill. This setting |
| | | uses the two pins on the level |
| | | connector. |
| REMOTE START/STOP | START/STOP (YES/NO) | Setting for starting or stopping the |
| | CONTACT (N.O./N.C.) | pump remotely. One single pin is |
| | | used in this case. The pump starts |
| | | used in this case. The pullip starts |

| | | blocks when the contact is open (or vice-versa, depending on the N.O. or N.C. contact). |
|----------|--|--|
| OVERFLOW | ALARM (YES/NO) LIGHT ALARM (YES/NO) STOP OR WORK | In PPM, MLQ, and Percentage modes, you can activate an alarm (overflow) to block (STOP) or run (WORK) the pump if the flow rate calculation exceeds the flow rate set during the calibration stage. |

3.5 Alarm log

The alarm log contains all the triggered alarms. Select the reset icon to reset an alarm.

ALARM REGISTER PR014 - 24/05/18 - 18:20

Ċ

The alarms are summarised in Table .

Table 8 Alarms

| ALARM | | | | VISUAL |
|-------|-----------------------------|---------------------|---|----------------------|
| CODE | CODE ALARM TYPE DESCRIPTION | | CAUSE | FEEDBACK (SCREEN) |
| TOU01 | ELECTRONICS HARDWARE | TIMEOUT | Failed communication between two microcontrollers | (SCREEN) |
| CUR02 | ELECTRONICS HARDWARE | OVER CURRENT | The motor current exceeds the limit | |
| ТЕМОЗ | ELECTRONICS HARDWARE | OVER TEMPERATURE | The temperature exceeds the board limits. | FLASHING RED |
| OVB04 | ELECTRONICS HARDWARE | OVER BUS | Voltage exceeds the sheet limits | |
| INR05 | ELECTRONICS HARDWARE | INRUSH | Inrush relays broken | |
| TRI06 | MOTOR HARDWARE | TRIP | Motor short circuit | |
| PRO07 | FUNCTIONAL | PROXIMITY | Motor or Pump block | |
| DFL08 | FIRMWARE | DATA FLASH | Data setting error | FLASHING |

| EFL09 | FIRMWARE | EXT FLASH | Log write error and FW update error | YELLOW |
|-------|-------------|-------------|-------------------------------------|--------------|
| RTC10 | ELECTRONICS | RTC | Clock error upon | |
| | HARDWARE | | power-on (the clock is | |
| | | | set to a non-admitted | |
| | | | time). Flat battery. | |
| LOG11 | FIRMWARE | LOG | Error in recording the | |
| | | | file log | |
| LVL12 | PROCESS | LEVEL | STOP input of the level | FIXED RED |
| | | | sensor | |
| OVR13 | PROCESS | OVERFLOW | Overflow alarm | FIXED RED OR |
| | | | | FIXED YELLOW |
| RMT14 | PROCESS | REMOTE STOP | Alarm resulting from | FIXED RED |
| | | | remote stop | |
| AMA15 | PROCESS | ANALOG mA | Input current beyond | FIXED RED |
| | | | the range set in the | |
| | | | analog mA mode. | |
| AVA16 | PROCESS | ANALOG V | Input voltage beyond | FIXED RED |
| | | | the range set in the | |
| | | | analog V mode. | |
| UVG17 | ELECTRONICS | | Power supply voltage | |
| UVB18 | HARDWARE | | too low. | |

3.6 Analog Mode Calibration Procedure

The scope of the following procedure is to calibrate analog output and input mA signal to let the pump recognize 4 mA and 20 mA. When the measured value by PRO KIT is quite different from the input value (at least 0,3 mA difference), this procedure will help the accuracy of 4-20 mA signal.

Disable Analog Output

The first operation to be accomplished is to disable analog mA output:

- 1) Go to the menu "settings→Analog output"
- 2) Set the analog output to "NO" clicking on it

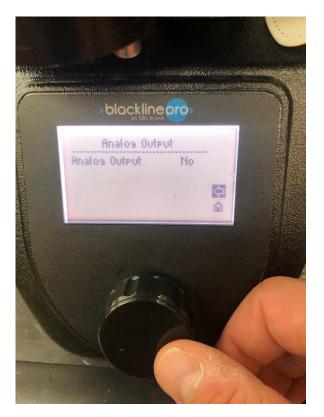


Figure 13

Loop installation

To the signal, the items required are:

Analog input:

- 1) Power loop (max 14 Vdc voltage in parallel on the pins)
- 2) Multimeter to measure 4-20 mA

Analog output:

- 3) Power loop (max 48 Vdc)
- 4) Multimeter to measure 4-20 mA

The loop must be connected to PRO according to the cables table described in the manual.

The multimeter shall be connected in series to close the loop and measure current. Please refer to

multimeter manual for connection specifications.

Calibration

To calibrate the analog signal the necessary operations are the followings:

- 1) Power up the loop for analog input signal.
- 2) Go to the menu "setting→calibration"
- 3) Click the handwheel for 10 sec until will appear 3 new fields
 - a. Analog ma
 - b. Analog V
 - c. Analog Output
- 4) Click on analog input
- 5) A window with 2 values "4 mA" and "20 mA" will appear and a value on the bottom of the screen is proportional to the input current.
- 6) To calibrate 4 mA input signal:
 - a. Set current input at 4 mA.
 - b. Click on 4 mA (1100 as default)
 - c. Change the value
 - d. The value the bottom of the screen will change.
 - e. Change the value close to 4 mA to reach the value at the bottom of the screen.
- 7) To calibrate 20 mA input signal:

- a. Set current input to 20 mA.
- b. Click on 20 mA (2300 as default)
- c. Change the value
- d. The value of current at the bottom of the screen will change.
- e. Change the value close to 4 mA to reach the value at the bottom of the screen.
- 8) Click on the down arrow to memorize the calibrated value. (do not push the left arrow otherwise you have to calibrate 4 mA and 20 mA newly).
- 9) Confirm the selection and go back to the previous menu.
- 10) Click on analog output (if needed)



Figure 14

11) <u>A window with 2 values "4 mA" and "20 mA</u>" will appear.



Figure 15

- 12) To calibrate 4 mA signal:
 - a. click on 4 mA (1100 in the picture above)
 - b. change the value
 - c. the value of current measured by the multimeter shall change
 - d. Change the value until the multimeter will measure the desired 4 mA
- 13) To calibrate 20 mA signal:
 - a. click on 20 mA (2300 in the picture above)
 - b. change the value
 - c. the value of current measured by the multimeter shall change
 - d. Change the value until the multimeter will measure the desired 20 mA

14) Click on the down arrow to memorize the calibrated value. (do not push the left arrow otherwise you have to calibrate 4 mA and 20 mA newly).

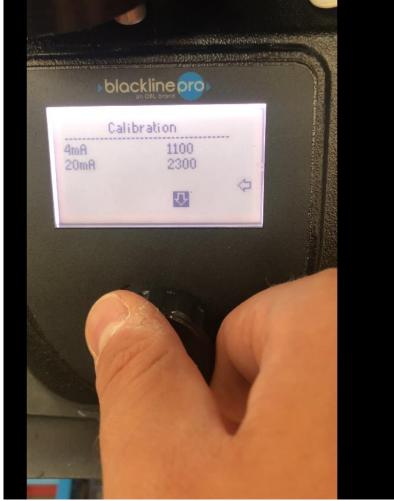


Figure 16

15) Confirm the selection.

3.7 Modbus

Table 9 Modbus Specification

| MODBUS SPECIFICATION | | | | | | |
|-------------------------------|---|--|--|--|--|--|
| Serial interface | RS 485 half duplex | | | | | |
| Protocol | MODBUS-RTU | | | | | |
| Baud rate | 2400-4800-9600-19200-38400-57600-115200 bps | | | | | |
| Start bit | 1 | | | | | |
| Data lenght | 8 bit | | | | | |
| Parity bit | N. A. | | | | | |
| Stop bit | 1 | | | | | |
| Cyclic Redundancy Check (CRC) | CRC-16 | | | | | |
| ID slave address | 1 to 247 | | | | | |
| Modbus paramerters registers | Da 40001 a 40058 | | | | | |

| Modbus commands registers | Da 41001 a 41016 | | | |
|--|--|--|--|--|
| Registers that can be read with 1 command | 58 | | | |
| Registers that can be written with 1 command | 58 | | | |
| Function Codes | 03 (03 hex) – read holding register | | | |
| Tunction codes | 16 (10 hex) – preset multiple holding register | | | |
| | 01 (01 hex) – illegal function | | | |
| Exclusion Codes | 02 (02 hex) – illegal data value | | | |
| Exclusion codes | 03 (03 hex) – illegal data address | | | |
| | 07 (07 hex) – NAK | | | |

The user can activate MODBUS functionality in settings menu.

| MODBUS | | |
|----------------------------------|----------------------|---|
| MODBUS BAUD RATE INDIRIZZO | YES 9600 bps 1 | |
| | | Ċ |

Figure 17 Modbus settings

In MODBUS window, the user can:

- 1. activate MODBUS (YES/NO)
- 2. set the baud rate (2400-4800-9600-19200-38400-57600-115200 bps).
- 3. set the slave device address

When MODBUS is active, the user can locally do the following operations:

- 1. When the motor is ON
 - a. To stop the pump (selecting STOP icon)
 - b. To display statistics
- 2. When the motor is OFF:
 - a. To navigate in the menu
 - b. It is not possible to start up the motor. The user has to turn off MODBUS mode to start up the motor.

When MODBUS is active, an icon will appear on the right corner of all windows of the firmware.



Figure 18 Modbus opertating mode

COMMUNICATION EXAMPLE

Black Line PRO can communicate with a PLC using MODBUS interface.

Examples of communications are described hereinafter:

Read Holding Registers (Function Code 03)

 Request:

This command is requesting the content of holding registers 40024 to 40025 from the slave device with address 01.

| 01 03 0017 | 0002 740F |
|-------------|--|
| 01: | Slave Address (01 hex) |
| 03: | Function Code (Read holding registers) |
| 0017: | The Data Address of the first register requested. (40024 - 40001 = |
| 17 hex) | |
| 0002: | The total number of registers requested. (read 2 registers 40024 to |
| 40025) | |
| 740F: | CRC (cyclic redundancy check) for error checking. |
| Response: | |
| 01 03 04 00 | 3C 003C 3A2E |
| 01: | Slave Address (01 hex) |
| 03: | Function Code (Read holding registers) |
| 04: | The number of data bytes to follow (2 registers x 2 bytes each = 4 |
| bytes) | |
| 003C: | The contents of register 40024 |
| 003C: | The contents of register 40025 |
| | |

- 3A2E: The CRC (cyclic redundancy check).
- 2. Preset Multiple Registers (FC=16)
 - a. Request

b.

This command is writing the contents of two holding registers 41003 and 41004 to the slave device with address 01.

01 10 03EA 0002 04 0000 0000 6968

- 01: The Slave Address (01 hex)
- 10: The Function Code (Preset Multiple Registers)
- 03EA: The Data Address of the first register. (41003 40001 = 03EA hex)
- 0002: The number of registers to write
- 04: The number of data bytes to follow (2 registers x 2 bytes each = 4
- bytes)
- 0000: The value to write to register 41003
- 0000: The value to write to register 41004
- 6968: The CRC (cyclic redundancy check) for error checking.

b. Response

01 10 03EA 0002 6078

| 01: | The Slave Address (01 hex) |
|-------|--|
| 10: | The Function Code (Preset Multiple Registers) |
| 03EA: | The Data Address of the first register. $(41003 - 40001 = 03EA hex)$ |
| 0002: | The number of registers written. |
| 6078: | The CRC (cyclic redundancy check) for error checking. |

- 3. Read Holding Registers (FC=03) ERROR
 - a. Request
 - This command is requesting the content of analog output holding registers 40100 (register out of range) from the slave device with address
 - 01 03 9CA3 0001 5A78
 - b. Response
 - 01 83 02 COF1

| 01: | The Slave Address (01 hex) |
|-------|---|
| 83: | The Function Code (Preset Multiple Registers) with 1 to MSB |
| 02: | error code (illegal data address) |
| COF1: | The CRC (cyclic redundancy check) for error checking. |

MODBUS LIST

The list of the registers and parameters that the user can write/read using Modbus is described in the following table:

Table 10 Modbus list

| Nr. | PAR. | TYPE | TYPE | BYTE | Min | Max | Default | U.M. | Description |
|-------|-----------|-------|-------|------|-------|-------|---------|-----------|--------------------------------|
| Reg. | | MOTOR | MOTOR | | value | value | | | |
| | | OFF | ON | | | | | | |
| 40001 | M_TIME_S | W/R | R | 2 | 1 | 120 | 60 | S | Calibration time - calibration |
| | | | | | | | | | settings |
| 40002 | M_FLOW | W/R | R | 2 | 1 | 9999 | 600 | (L/h or | Max flowrate - pump capacity |
| | | | | | | | | Gal/h)*10 | settings |
| 40003 | M_PERC | W/R | R | 2 | 1 | 100 | 50 | % | Adjustment % - pump capacity |
| | | | | | | | | | settings |
| 40004 | M_L_PULSE | W/R | R | 2 | 1 | 2000 | 200 | L/p or | L/pulse o pulse/L |
| | | | | | | | | p/L | |
| 40005 | | W/R | R | 2 | 0 | 5 | 1 | | Languages |
| | | | | | | | | | Value 0= Italian |
| | | | | | | | | | Value 1=English |
| | | | | | | | | | Value 2=Spanish |
| | | | | | | | | | Value 3=Dutch |
| | | | | | | | | | Value 4=Russian |
| | | | | | | | | | Value 5=French |
| 40006 | M_FDATE | W/R | R | 2 | 0 | 2 | 0 | | Date Format |
| | | | | | | | | | Value 0=DD/MM/YY |
| | | | | | | | | | Value 1=MM/DD/YY |
| | | | | | | | | | Value 2=YY/MM/DD |
| 40007 | M_24H | W/R | R | 2 | 0 | 1 | 0 | | Time Format |
| | | | | | | | | | Value 0=24h |
| | | | | | | | | | Value 1=12 h |
| 40008 | M_UNIT_LH | W/R | R | 2 | 0 | 1 | 0 | | Unit of measure |
| | | | | | | | | | Value 0=L/h |
| | | | | | | | | | Value 1=Gal/h |
| 40009 | M_YES_NO | W/R | R | 2 | 0 | 1 | 1 | | Proximity red alarm |
| | | | | | | | | | Value 0=No |
| | | | | | | | | | Value 1=Yes |

| 40010 | M_YES_NO | R | R | 2 | 0 | 1 | 0 | 1 | MODBUS activation |
|-------|--------------|--------|-----|---|----------|-------|------|-----------|----------------------------------|
| | | | | | | | | | Value 0=No |
| | | | | | | | | | Value 1=Yes |
| 40011 | M_YES_NO | W/R | R | 2 | 0 | 1 | 1 | | Analog output |
| | | , | | | | - | | | Value 0=No |
| | | | | | | | | | Value 1=Yes |
| 40012 | M_RELAY | W/R | R | 2 | 0 | 1 | 1 | | Relay output activation |
| 10012 | | in, ix | | - | Ŭ | - | - | | Value 0=Off |
| | | | | | | | | | Value 1=START/STOP |
| | | | | | | | | | Value 2=Alarm |
| 40013 | M_COLOR | W/R | R | 2 | 1 | 5 | 2 | | Display color |
| 10015 | | WIN | i v | - | - | J | 2 | | Value 1=Display OFF |
| | | | | | | | | | Value 2=Green |
| | | | | | | | | | Value 3=Pink |
| | | | | | | | | | Value 4=Light blue |
| | | | | | | | | | Value 5=Blue |
| 40014 | M | \\//D | R | 2 | 0 | 100 | 50 | % | |
| | M_PERC | W/R | | | - | | | % | Display contrast |
| 40015 | M_YES_NO | W/R | R | 2 | 0 | 1 | 0 | | Red alarm display level and |
| | | | | | | | | | remote control |
| | | | | | | | | | Value 0=No |
| | | | | | | | | | Value 1=Yes |
| 40016 | M_YES_NO | W/R | R | 2 | 0 | 1 | 0 | | Red alarm display overflow |
| | | | | | | | | | Value 0=No |
| | | | | | | | | | Value 1=Yes |
| 40017 | M_YES_NO | W/R | R | 2 | 0 | 1 | 0 | | START/STOP remote control |
| | | | | | | | | | alarm |
| | | | | | | | | | Value 0=No |
| | | | | | | | | | Value 1=Yes |
| 40018 | M_CONTACT | W/R | R | 2 | 0 | 1 | 0 | | Remote control contact |
| | | | | | | | | | Value 0=NO |
| | | | | | | | | | Value 1=NC |
| 40019 | M_YES_NO | W/R | R | 2 | 0 | 1 | 0 | | Red alarm display overflow |
| | | | | | | | | | Value 0=No |
| | | | | | | | | | Value 1=Yes |
| 40020 | M_STOP_WORK | W/R | R | 2 | 0 | 1 | 0 | | STOP/WORK overflow settings |
| | | | | | | | | | Value 0=STOP |
| | | | | | | | | | Value 1=WORK |
| 40021 | M_FLOW | W/R | R | 2 | 1 | 9999 | 600 | (L/h o | Flowrate constant mode |
| | | | | | | | | Gal/h)*10 | |
| 40022 | M_VOLUME_INT | W/R | R | 2 | 1 | 65535 | 1000 | L o Gal | Volume batch mode |
| 40023 | M_FLOW | W/R | R | 2 | 1 | 9999 | 600 | (L/h o | Flowrate batch mode |
| | | | | | | | | Gal/h)*10 | |
| 40024 | M_MINUTE | W/R | R | 2 | 1 | 255 | 60 | min | Working time pause-work mode |
| | | | | | | | | | |
| 40025 | M_MINUTE | W/R | R | 2 | 1 | 255 | 60 | min | Pausetime pause-work mode |
| 40026 | | | D | | F | 20 | 20 | | High value summert 4.20 |
| 40026 | DIP_MIN | W/R | R | 2 | 5 | 20 | 20 | mA | High value current 4-20 mA |
| 40007 | | | | | | 20 | | | analog mA |
| 40027 | DIP_MAX | W/R | R | 2 | 4 | 20 | 4 | mA | Low value current 4-20 mA analog |
| | | | | 1 | <u> </u> | 1 | l | | l |

| | | | | | | | | | mA |
|--------|-----------------|-------|---|---|---|-------|-----|---------------------|--|
| 40028 | DIP_MIN | W/R | R | 2 | 1 | 9999 | 600 | (L/h o | Max flowrate analog mA mode |
| | _ M_FLOW | | | | | | | Gal/h)*10 | 5 |
| 40029 | DIP_MAX | W/R | R | 2 | 0 | 9999 | 0 | (L/h o | Min flowrate analog mA mode |
| | M_FLOW | | | | | | | Gal/h)*10 | |
| 40030 | DIP_MIN | W/R | R | 2 | 1 | 10 | 10 | V | High value voltage 0-10 V analog |
| | | | | | | | | | V mode |
| 40031 | DIP_MAX | W/R | R | 2 | 0 | 10 | 0 | V | Low value voltage 0-10 V analog |
| 40000 | | | | | | | 600 | | V mode |
| 40032 | | W/R | R | 2 | 1 | 9999 | 600 | (L/h o Gal/h)*10 | Max flowrate analog V mode |
| 40022 | M_FLOW | 14//D | | | 0 | 0000 | 0 | | Min flaumata angles) (mada |
| 40033 | DIP_MAX | W/R | R | 2 | 0 | 9999 | 0 | (L/h o Gal/h)*10 | Min flowrate analog V mode |
| 40034 | M_FLOW M_U16 | W/R | R | 2 | 1 | 65535 | 100 | PPM | PPM desired in the tank PPM |
| 40034 | M_010 | W/K | к | 2 | | 62232 | 100 | PPM | mode |
| 40035 | M_PERC | W/R | R | 2 | 1 | 100 | 100 | % | Concentration dosed fluid PPM |
| | | | | | | | | | mode |
| 40036 | M_PERC | W/R | R | 2 | 1 | 100 | 100 | % | Concentration in the tank |
| | | | | | | | | | percentage mode |
| 40037 | M_PERC | W/R | R | 2 | 1 | 100 | 100 | % | Concentration dosed fluid |
| | | | _ | | | | 100 | | percentage mode |
| 40038 | M_U16 | W/R | R | 2 | 1 | 1000 | 100 | MLQ | MLQ desired in the tank MLQ mode |
| 40039 | M_PERC | W/R | R | 2 | 1 | 100 | 100 | % | Concentration dosed fluid MLQ |
| | | | | | | | | | mode |
| 40040 | DIP_MIN | W/R | R | 2 | 2 | 1000 | 2 | p/m | High value pules p/m pulse mode |
| | M_P_M | | | | | | | | |
| 40041 | DIP_MAX | W/R | R | 2 | 1 | 1000 | 1 | p/m | Low value pules p/m pulse mode |
| | M_P_M | | | | | | | | |
| 40042 | DIP_MIN | W/R | R | 2 | 1 | 9999 | 600 | (L/h o | Max flowrate pulse mode |
| | M_FLOW | | | | | | | Gal/h)*10 | |
| 40043 | DIP_MAX | W/R | R | 2 | 0 | 9999 | 0 | (L/h o | Min flowrate pulse mode |
| | M_FLOW | | _ | | | | | Gal/h)*10 | |
| 40044 | M_PRESSURE | W/R | R | 2 | 1 | 300 | 1 | Bar | Calibration pressure – calibration window |
| 40045 | M_TYPE_START | W/R | R | 2 | 0 | 1 | 0 | | Batch start |
| | | | | | | | | | Value 0=manual |
| | | | | | | | | | Value 1=external |
| 40046 | M_FLOW | W/R | R | 2 | 1 | 9999 | 600 | (L/h o | Flowrate pause work mode |
| | | | | | | | | Gal/h)*10 | |
| 40047 | M_CONTACT | W/R | R | 2 | 0 | 1 | 0 | | Contact output relay |
| | | | | | | | | | Value 0=NO |
| | | | | | | | | | Value 1=NC |
| 40048 | M_YES_NO | W/R | R | 2 | 0 | 1 | 0 | | Level START contact activation |
| | | | | | | | | | Value 0=No |
| 400.10 | | W//D | D | | | - | | | Value 1=Yes |
| 40049 | M_YES_NO | W/R | R | 2 | 0 | 1 | 0 | | Level STOP contact activation |

| | l | 1 | 1 | 1 | 1 | 1 | I | 1 | Value 0=No |
|-------|------------|--------------|-------|---|-------------------|-------|--------|--------|-----------------------------------|
| | | | | | | | | | Value 1=Yes |
| 40050 | M_CONTACT | W/R | R | 2 | 0 | 1 | 0 | | Level START contact |
| | | , | | _ | | _ | | | Value 0=NO |
| | | | | | | | | | Value 1=NC |
| 40051 | M_CONTACT | W/R | R | 2 | 0 | 1 | 0 | | Level STOP contact |
| | | , | | - | Ū | - | ° | | Value 0=NO |
| | | | | | | | | | Value 1=NC |
| 40052 | M_YES_NO | W/R | R | 2 | 0 | 1 | 1 | | Menù light |
| | | , | | - | Ū | - | - | | Value 0=No |
| | | | | | | | | | Value 1=Si |
| 40053 | M_BAUD | R | R | 2 | 0 | 6 | 0 | | Baudrate MODBUS |
| 10035 | 11_0/100 | i c | | - | Ŭ | Ũ | ° | | Value 0=2400 |
| | | | | | | | | | Value 1=4800 |
| | | | | | | | | | Value 2=Verde |
| | | | | | | | | | Value 3=Rosa |
| | | | | | | | | | Value 4=Azzurro |
| | | | | | | | | | Value 5=Blu |
| 40054 | M_TIME_S | W/R | R | 2 | 1 | 120 | 120 | s | Pulses time out in pulse mode, |
| | | , | | - | - | | | 5 | PPM mode, concentration mode e |
| | | | | | | | | | MLQ mode |
| 40055 | M_AMPERE | W/R | R | 2 | 10 | 35 | 20 | | Motor current calibration window |
| | M_50_60Hz | W/R | R | 2 | 0 | 1 | 0 | | 50/60 Hz |
| | | W/R | R | 2 | 0 | 1 | 0 | | L/pulse pulse/L in PPM, MLQ e |
| 10037 | M_LF_FL | VV/K | ĸ | 2 | 0 | 1 | 0 | | percentage modes |
| 40058 | MIIR | R | R | 2 | 1 | 247 | 1 | | MODBUS ID |
| 40058 | M_08 | K W/R | W/R | 2 | 1 | 10 | 1 | uint16 | Operating modes |
| 41001 | MODE | W/R | W/R | 2 | 1 | 10 | 1 | umuto | , 5 |
| | MODE | | | | | | | | Value 1=Constant Value 2=Batch |
| | | | | | | | | | Value 3=Pause-work |
| | | | | | | | | | Value 4=Weekly |
| | | | | | | | | | Value 5=Analog mA |
| | | | | | | | | | Value 5=Analog MA |
| | | | | | | | | | Value 7=PPM |
| | | | | | | | | | Value 8=Percentage |
| | | | | | | | | | Value 9=MLQ |
| | | | | | | | | | Value 10=Pulse |
| 41002 | START-STOP | W/R | W/R | 2 | 0 | 2 | 0 | uint16 | Starting motor |
| 41002 | STARTSTO | VV/IX | VV/IX | 2 | Ŭ | 2 | 0 | unicio | Value 0=Stop |
| | | | | | | | | | Value 1=Start |
| | | | | | | | | | Value 2=Standby |
| 41003 | ALARMS | W/R | W/R | 4 | This | value | can be | uint3 | These registers inform the user |
| 11005 | | VV/ R | VV/K | 4 | written only to 0 | | | unto | about alarms according to the |
| | | | | | white | | 0 | | position of the bit |
| 41004 | | | | | 4 | | | | BIT 0 "UVG17",//UNDER BUS |
| 71004 | | | 1 | | 1 | | | | GO |
| | | | 1 | | 1 | | | | BIT 1 "UVB18",//UNDER BUS |
| | | | 1 | | 1 | | | | GO |
| | | | 1 | | 1 | | | | BIT 2 "TOU01",//TIME OUT |
| | | | | | 1 | | | | |

| | | | | | | | | | | BIT 3 | "CUR02",//OVER |
|-------|--------------|-----|-----|---|--|--------|-------|--------------------------|---------------------------------|---------------------|-----------------------------|
| | | | | | | | | | CURRENT | | |
| | | | | | | | | | | BIT 4 | "TEM03",//OVER |
| | | | | | | | | | | | TEMPERATURE |
| | | | | | | | | | | BIT 5 | "OVB04",//OVER BUS |
| | | | | | | | | | | BIT 6 | "INR05",//INRUSH |
| | | | | | | | | | | BIT 7 | "TRI06",//TRIP |
| | | | | | | | | | | BIT 8 | "PRO07",//PROXIMITY |
| | | | | | | | | | | BIT 9 | "DFL08",//DATA FLASH |
| | | | | | | | | | | BIT 10 | "EFL09",//EXT FLASH |
| | | | | | | | | | | BIT 11 | "RTC10",//RTC |
| | | | | | | | | | | BIT 12 | "LOG11",//LOG |
| | | | | | | | | | | BIT 13 | "LVL12",//STOP LEVEL |
| | | | | | | | | | | BIT 14 | "OVR13",//OVERFLOW |
| | | | | | | | | | | BIT 15 | "RMT14",//REMOTE |
| | | | | | | | | | | BIT 16 | "AMA15",//ANALOG mA |
| | | | | | | | | | | BIT 17 | "AVA16",//ANALOG V |
| 41005 | PARTIAL LIFE | W/R | W/R | 4 | This | value | са | n be | minutes | Durata | della vita parziale della |
| | | | | | written only to 0 | | | | pompa. | Scrivendo a zero il | |
| 41006 | | | | | | | | | | registro | si resetta questo valore |
| | | | | | | | | | | nel firm | ware. |
| 41007 | PARTIAL | W/R | W/R | 4 | This value can be written only to 0 | | L*100 | Volume | parziale in litri erogato | | |
| | VOLUME L | | | | | | | dalla po | ompa. Scrivendo a zero il | | |
| 41008 | | | | | 1 | | | | | registro | si resetta questo valore |
| | | | | | | | | | | nel firm | ware. |
| 41009 | PARTIAL | W/R | W/R | 4 | This | value | са | n be | Gal*100 | Volume | parziale in galloni erogato |
| | VOLUME Gal | | | | writter | n only | to 0 | | | dalla po | ompa. Scrivendo a zero il |
| 41010 | | | | | | | | | | registro | si resetta questo valore |
| | | | | | | | | | | nel firm | ware. |
| 41011 | ADJUSTMENT | R | R | 2 | | | | | % | Adjustm | nent |
| 41012 | MOTOR | R | R | 2 | | | % | Frequency % of the motor | | | |
| 41013 | FLOW/VOL. | R | R | 4 | LSB | | | float | Flowrate or volume displayed on | | |
| 41014 | | | | | MSB | | | | the screen | | |
| 41015 | INFO | R | R | 4 | LSB | | | float | Sec, mA, V, flowrate, input, | | |
| 41016 | | | | | MSB | | | | | p/m dis | played on the screen |

6 MAINTENANCE

1 ROUTINE MAINTENANCE

Routine maintenance includes operations that are carried out based on the operator's common sense, without following a strict schedule.



HAZARD

Do not carry out routine maintenance operations on mains-powered equipment.

Routine maintenance operations carried out by the user:





Frequently clean the pump. Dirt and residues must not cover the adjustments or the interface screen.

2 TROUBLESHOOTING

To make a self-diagnosis of the product, see subchapter "Alarm log".

Contact the manufacturer if you detect defects and/or malfunctions that are not described in this manual.

7 ACCESSORIES AND SPARE PARTS

1 ASSISTANCE

Contact the manufacturer for any information relative to installation, use, and maintenance of the product.

For the sake of clarity, the client must always refer to this manual and the instructions listed.

2 SPARE PARTS



ALWAYS USE ORIGINAL SPARE PARTS. FOR ANY SPARE PART, CONTACT THE MANUFACTURER.

The following spare parts are available for the KIT PRO:

Table 11 Spare parts

| Spare part kit code | Description | KIT component code | Description | | |
|------------------------|---------------------------------|--------------------------|---------------------------------|--|--|
| KME60 | Connection cables (4 pieces) | KME60 | Connection cables (4 pieces) | | |
| KPRA08 | Proximity sensor | KPRA08 | Proximity sensor | | |
| | Spare part kit for | P20.2189 | Pump connection | | |
| KKPRO | routine | KMV150 | Knob | | |
| | maintenance | P20.2193 | Front label | | |

We do not recommend using non-original spare parts. If you decide to use them, all the Warranty terms and conditions, if still valid, will be void and null and the Manufacturer will not be held responsible for any damage to people and/or property.

8 ADDITIONAL INSTRUCTIONS

1 DECOMMISSIONING AND DISASSEMBLY

It is the user's responsibility to comply with the procedures and regulations in the countries of operation, regarding disposing of waste resulting from maintenance (consumption material) or the demolition of equipment.

"Waste" is intended as any substance or object which the holder has decided to or is required to discard. Waste is classified according to the origin, in "urban waste" and "special waste" and, according to harmfulness, in "hazardous waste" and "non-hazardous waste".

Maintenance or demolition pump waste are classified as "special waste" only if properly cleaned. Otherwise, they are to be considered "HAZARDOUS special waste".

Special waste" and "urban waste", and especially "hazardous" and "non-hazardous" waste, must never be mixed."

Briefly summarising:

- "special waste" must not be disposed of as "urban waste"
- this waste must be collected separately using public or private collection systems required by local laws (in an approved collection centre)
- due to its use, this equipment may contain hazardous substances. Improper disposal can have adverse effects on human health and the environment.
- administrative sanctions exist in the case of improper disposal of or abuse of waste

 \wedge

Disposal of substances into sewers or abandoning waste in the environment is strictly

prohibited. Contact your local waste disposal service to receive adequate and accurate information regarding disposal.